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# From the Geo-dipole to the Geo-multipole: A Framework of Applying Multiple-Point (Geo)Statistics for Geographic Field Analysis

#### Rui Zhu

STKO Lab, Department of Geography University of California, Santa Barbara

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Spatial Pat	tterns			

#### • Types of spatial patterns



- How to quantify spatial pattern?
  - First-order or environmental effects: is the attribute mean stationary across the domain?
    - e.g., local intensity and local mean of the attribute value.
  - Second-order or interaction effects: is there any correlation between locations?
    - e.g., spatial association

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 Second-order
 Interactions

How to model spatial interactions?

- Single distance class:
  - Geary's C

$$C = \frac{(N-1)\sum_{i}\sum_{j}\mathbf{w}_{ij}(X_{i}-X_{j})^{2}}{2\sum_{i}\sum_{j}\mathbf{w}_{ij}\sum_{i}(X_{i}-\bar{X})^{2}}$$

• Moran's I

$$I = \frac{N}{\sum_{i}\sum_{j} \mathbf{w}_{ij}} \frac{\sum_{i}\sum_{j} \mathbf{w}_{ij}(X_{i} - \bar{X})(X_{j} - \bar{X})}{\sum_{i}(X_{i} - \bar{X})^{2}}$$

- Ø Multiple distance classes:
  - Semivariance

$$\hat{\gamma} = \frac{1}{2N(\mathbf{h})} \sum_{i=1}^{N(\mathbf{h})} [X(s_i + \mathbf{h}) - X(s_i)]^2$$

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Sencod-order	Interactions			

Are these second-order statistics robust enough to analyze all spatial patterns?

• In some cases, they are:



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Second-order	Interactions			

Are these second-order statistics robust enough to analyze all spatial patterns?

• In some cases, they are not:

proportion of blue pixels = 0.28





Second-order	Interactions			
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What are the reasons that make the second-order interaction (e.g., semivariogram) fail?

- The interaction between location A and location B may be dependent on a third, or even more nearby location(s) C.
- Spatial patterns may sometimes have evident geometrical properties.

Therefore, models that could quantify **higher-order interactions** are needed!

Higher_order	Interactions			
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- What it is **(conceptualization)**: interactions among multiple (i.e., more than two) locations are modeled *simultaneously*.
- How to model it:
  - Similar to variograms, use the sample data to model the spatial pattern. However, the size of sample data sets is typically small for such multiple-point inference;
  - Multiple-Point (Geo)Statistics: The *training image* is applied as an analogue, or more generally a prior model of the target pattern; then a *template* is used for modeling the higher-order interactions (statistics).

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Geographic (	Conceptualization			

Goodchild et al., (1999, 2007)'s general theory of geographic representation in GIS:

• Geo-atom:

$$\langle x, Z, z(x) \rangle$$

where a spatial location x is associated with an attribute feature Z via the function mapping z(x).

• Geo-dipole:

where the interaction of variables between two locations x and x' is described via the two-point mapping z(x, x').

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Geo-multipole	2			

Following Goodchild's geo-dipole  $\langle x, x', Z, z(x, x') \rangle$ , we propose a generalized conceptualization for modeling spatial interactions:

**Geo-multipole:**  $\langle x, t_N, Z, z(x, t_N) \rangle$ where  $t_N = \{x_1, ..., x_N\}$  are the *N* neighbors of *x*.

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Geo-multipole	e			

Both the geo-atom and geo-dipole could be described by the geo-multipole:

- When *t<sub>N</sub>* is empty, the geo-multipole equals to the geo-atom, which is a *single-point* data model;
- When  $t_N = \{x'\}$ , the geo-multipole equals to the geo-dipole, which is a *two-points* data model;

• The most generalized version of geo-multipole, where  $t_N = \{x_1, ..., x_N\}$ , is a *multiple-points* data model.

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Geo-dipole V	S. Geo-multipole			

The key difference between the geo-dipole and the geo-multipole:

- **Geo-dipole**: interactions are considered in *pairs* under the conceptualization of the geo-dipole despite that multiple pairwise interactions could be combined in *sequence*;
- **Geo-multipole**: locations  $x_1, ..., x_N$  in  $t_N$  are *simultaneously* considered (along with the corresponding attribute values) when modeling their interactions with x.

Mathematically,  $f(z(x, x_1), ..., z(x, x_N))$  does not necessarily imply  $z(x, t_n = \{x_1, ..., x_N\})$ .

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Statistical Pe	erspectives			

Geographic fields are frequently assumed to be generated from stochastic processes, and are thus regarded as realizations of a random field. Therefore, the generalized geo-multipole, with its two special cases, are translated to their statistical perspectives (i.e., modeled as probability density/mass functions).

- Single-point data model (i.e., geo-atom)
- Two-points data model (i.e., geo-dipole)
- Multiple-points data model



Probability density function:

$$f(z,x) = prob(Z(x) = z \pm \epsilon)$$

- Statistics:
  - Continuous attributes: mean, standard deviation, quantiles ...
  - Categorical attributes: mode, the proportion of one specific category ...
- Examples:
  - Univariate (*f*(*z*, *x*)): could only be estimated by experts using physical models or experience;
  - Multivariate (f(z, z', x) = prob(Z(x) = z|Z'(x))): linear and non-linear models could be used for modeling the relation between z and z' that are co-located at location x.



Probability density function:

$$f(z, x, Z(x')) = prob(Z(x) = z | Z(x'))$$

- Statistics:
  - Continuous attributes: semivariogram, cross-semivariogram ...
  - Categorical attributes: indicator semivariogram, transition probabilities ...
- Examples:
  - Univariate (f(z, x, Z(x'))): interpolation (e.g., IDW, Kriging)
  - Multivariate

(f(z, z', Z(x'), Z'(x)) = prob(Z(x) = z|Z(x'), Z'(x))):contextual classification with multi-spectral remotely sensed images...



Probability density function:

$$f(z, x, Z(t_N)) = prob(Z(x) = z | Z(t_N))$$

- $\bullet$  Statistics: higher-order conditional probabilities ...  $\rightarrow$  But, how do we model it?
- Examples: interpolation, classification and simulation...

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Building Blo	cks			

- **Training images (***TI***)** that are assumed to contain the target spatial patterns;
- Template (T) for scanning training images;
- Data events (dev(x)), which are simultaneous (joint) combinations of attribute values at the template configuration.



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- Extended Normal Equations Simulation (ENESIM): Guardiano and Srivastava (1993)
- Simple Normal Equation Simulation (SNESIM): Strebelle (2002)
- Pattern-based Simulation (SIMPAT): Arpat (2005)
- Filter-based Simulation (FILTERSIM): Zhang et al. (2006)
- Direct Sampling (DS): Mariethoz et al. (2010)
- Parallel Multiple-point algorithm using a list approach (IMPALA): Straubhaar et al. (2011)











- Scan the training image using the template;
- Store the data events in a tree structure;
- Estimate the conditional probability:

 $prob(z(x) = c_k | t_N) = \frac{\#(z(x) = c_k | t_N)}{\sum_{i=1}^{K} \#(z(x) = c_i | t_N)}$ 

where  $c_k$  is the  $k^{th}$  class, and  $t_N = \{x_1, .., x_N\}$  are the *N* neighbors of *x* 

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Case Study				

Do we really need the geo-multipole to model real world geographic field information?

- Use two-point statistics and multiple-point statistics respectively to:
  - describe the spatial pattern;
  - simulate the spatial pattern.



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Descriptio	n of the Pattern			

#### Variogram-based analysis:



#### Directional semivariograms for the five patterns

# Description of the Pattern

**MPS-based analysis:** A data event's conditional probability is calculated as the frequency of occurrence:

$$prob(z(x) = 0|t_N) = \frac{\#(z(x) = 0|t_N)}{\#(z(x) = 0|t_N) + \#(z(x) = 1|t_N)}$$

		P(x  n1, , ns)			
Templates	Data Events	Patte	P(x=1 n, n=)	P/x=01 p; p;)	P(x=1  p, p,)
n:n:n) n:x:n) n:s:ns		0.000	1.000 0.400	0.600 0.300	0.400 0.700
		0.500	0.500	0.625	0.375
		0.500	0.500	0.000	1.000
		0.530	0.470	0.458	0.542
		0.610	0.390	0.487	0.513

Conditional multiple-point probabilities for patterns 1 and 4

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**Variogram-based simulation:** Unconditional moving average simulation via the Fast Fourier Transform (FFT) was used; the resulting continuous images were then thresholded using suitable cutoff values so as to reproduce the same proportion of black pixels as the corresponding original binary images.



Variogram-based simulations (pattern 1 and pattern 4)



**MPS-based simulation:** Unconditional SNESIM was used; template was set to  $80 \times 80$  squares.



#### MPS-based simulations (pattern 1 and pattern 4)

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Observations				

- Multiple-point (geo)statistics (MPS) could better distinguish spatial patterns that are visually different compared to variograms;
- The two simulations using MPS show obviously different patterns with pattern 1 showing more curvilinearity along the west-east direction, and pattern 4 showing more polygonal geometries;
- The MPS-based simulations are more similar to the ones from the original images compared to variogram-based simulation.

Therefore, the geo-multipole, specifically the MPS, indeed plays a role in spatial analysis.

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Conclusions				

- Discussed motivations for higher-order interactions;
- Proposed a generalized geographic conceptualization, with higher-order interaction included;
- Introduced an algorithm to model the higher-order interactions;
- Showed the strength of higher-order interaction in describing and simulating spatial patterns using real world geographic field information.

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Future Work				

- The application details of multiple-point (geo)statistics for quantifying spatial patterns in geographic phenomena should be further explored;
- Contextual classification and spatial simulation using higher-order interactions could be studied and improved;
- Methods of modeling higher-order interactions for other geographic information could be investigated.

Acknowledgement						
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